

## Distributed Systems

06. Exam 1 Review

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### Question 1

What problem can arise with a system that exhibits fail-restart behavior?

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**Stale state:** the system has an outdated view of the world when it starts up.

*Note: data gets lost or missed messages – that is true for fail-stop behavior as well*

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### Question 2

At 10:05.800, a client sends the server a request for the time. The server response arrives at 10:05.900 containing a time stamp of 10:05.850. Using Cristian's algorithm, to what value does the client set its clock?

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$$\text{offset} = (T_{\text{received}} - T_{\text{sent}}) \div 2$$

$$= (10:05.900 - 10:05.800) \div 2$$

$$= 0.1 \div 2 = 0.05$$

$$\text{New time} = T_{\text{server}} + \text{offset} = 10:05.850 + 0.05 = \mathbf{10:05.9}$$

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### Question 3

In the diagram of events shown, what is the Lamport timestamp of event f? Assume that all Lamport counters are initialized to 0 and incremented before events.

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**f = 5**

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### Question 4

Explain the distinction between receiving and delivering a message.

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Receiving = message arrives the computer

Delivering = message is presented to the application

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### Question 5

Moore's law states that the:

- (a) Number of computers on the Internet doubles approximately every two years.
- (b) Amount of data on the Internet doubles approximately every two years.
- (c) **Number of transistors in an integrated circuit doubles approximately every two years.**
- (d) Speed of a network doubles approximately every two years.

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### Question 6

Metcalfe's law addresses the:

- (a) Bandwidth of a communication network.
- (b) Number of redundant paths in a communication network.
- (c) Latency of a communication network.
- (d) Value of a communication network.

The value of a telecommunications network is proportional to the square of the number of connected users of the system.

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### Question 7

A network *partition* refers to:

- (a) A protected segment of the network for administrative tasks.
- (b) Each local area network within the Internet.
- (c) A type of fault where the network fragments into two or more disconnected sub-networks.
- (d) A file system that is shared among multiple systems on a network.

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### Question 8

A *Byzantine fault* is:

- (a) A fault that triggers other failures, also known as a cascading failure.
- (b) Any complex fault that is difficult to identify.
- (c) The case when a system does not behave as expected.
- (d) The situation when messages take longer to arrive than expected.

Instead of ceasing to work as with fail-stop, a Byzantine fault produces incorrect results.

(a) and (b) may be side-effects of a byzantine fault.

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### Question 9

Which is *NOT* a key design principle of the Internet?

- (a) Support the interconnection of different physical networks.
- (b) Provide reliable communication.
- (c) Use routers to move data between networks.
- (d) Not have centralized control of the network.

IP does not guarantee reliable, in-order delivery.

If reliability is needed, it must be provided at the edge in software.

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### Question 10

Piggybacked acknowledgements:

- (a) Prevent feedback implosion.
- (b) Incorporate an acknowledgement within a response message.
- (c) Optimize network use by sending one acknowledgement for multiple messages.
- (d) Are a way for the sender to acknowledge receipt of an acknowledgement.

(a) Feedback implosion  
– Send a multicast message out and get replies from all group members

(c) Sending one ack for multiple messages  
– This is a cumulative acknowledgement

(d) Protocols generally do not acknowledge receipt of acks

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### Question 11

To convert a big endian number to a little endian format requires:

- (a) Losing precision.
- (b) Using fewer bytes.
- (c) Risking overflow.
- (d) Reversing byte positions.

• Endianness refers to the order in which bytes are arranged in multi-byte values

• Big endian = most significant byte at the lowest address

• To convert big endian to little, swap the bytes around

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### Question 12

An RPC server *skeleton* (stub):

- (a) **Receives requests from clients and calls the local function on the server.**
- (b) Is an automatically-generated template for writing server functions.
- (c) Is used to discover remote procedures that reside on the server.
- (d) Is called when the server-side function cannot be found.

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- (b) It's automatically generated server code but its purpose is not to be a template
  - (c) A name server is used for this (e.g., *portmap* on Linux)
  - (d) There's no "default" service that is called if the real service cannot be found

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### Question 13

*Marshaling* is the process of:

- (a) **Converting parameters into a network message for a remote procedure call.**
- (b) Sending a message that invokes a remote procedure call.
- (c) The setup process that is needed before any remote procedures can be called.
- (d) The process of a server receiving a message with parameters and calling the appropriate function.

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### Question 14

An *interface definition language* in remote procedure calls:

- (a) **Describes the input and return parameters of remote functions.**
- (b) Defines the protocol used to communicate with an RPC server.
- (c) Is the language used to implement remote procedure calls.
- (d) Is used to inform clients of available web services.

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- An IDL is used to generate client & server stubs.

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### Question 15

*Idempotent* functions are desirable for remote services because:

- (a) They are functional without the need to manage objects.
- (b) **We do not have to worry if multiple copies of the same request are received.**
- (c) They take no parameters, so data serialization is not an issue.
- (d) They are architecture independent and can migrate to different servers.

*Idempotent function* = may be called multiple times without side-effects

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### Question 16

REST differs from web services such as SOAP because:

- (a) There is no need to marshal data.
- (b) HTTP is used as the protocol for sending & receiving content.
- (c) **Requests are formulated as URLs.**
- (d) Returned data is structured as an XML message.

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(a) Marshaling is just converting parameters to an agreed-upon, pointerless format – a bunch of bytes. In REST, the parameters on a request would be marshaled as parameters in the URL

- (b) HTTP is used for SOAP services too
- (d) Not necessarily – can be JSON. SOAP uses XML.

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### Question 17

A surrogate process in Microsoft Windows is used to:

- (a) Route client requests to the correct server.
- (b) Act as the client stub and handle marshaling.
- (c) Handle all requests for undefined services.
- (d) **Load COM objects at the server based on client requests.**

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### Question 18

An advantage of *remote reference counting* over leasing is:

- (a) It is more fault tolerant.
- (b) Its enables shorter messages.
- (c) It consumes fewer resources on the client.
- (d) **It allows a server to deactivate an object immediately.**

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- (a) Remote reference counting is less fault tolerant.
  - (b) Not really. You still need to identify the object ... send an *increment/decrement* directive vs. *in-use*.
  - (c) Not really. The server still needs to keep track of objects in use.
  - (d) Yes – don't have to wait for lease expiration.

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### Question 19

The coordinator's clock in a Berkeley algorithm reads 1:00. The clocks on the other systems read 1:01, 1:02, 1:05. After running the algorithm, to what value will the other systems be set?

- (a) 1:00
- (b) 1:01
- (c) **1:02**
- (d) 1:05

The Berkeley algorithm just averages out all the times:

$$(1:00 + 1:01 + 1:02 + 1:05) \div 4 \\ = 4:08 \div 4 = 1:02$$

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### Question 20

A *synchronization subnet* is:

- (a) All the clients that are synchronizing from a specific NTP server
- (b) **A hierarchically arranged set of NTP servers**
- (c) A dedicated network for clock synchronization to ensure low jitter and low latency.
- (d) The set of protocols used to synchronize clocks (e.g., NTP, SNTP, PTP).

NTP synchronization subnet = collection of NTP servers

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### Question 21

Events  $x$ ,  $y$ ,  $z$  have Lamport timestamps of 3, 3, 5, respectively. They may or may not have occurred on different processes. What can you definitively say about these events?

- (a)  **$x$  and  $y$  are concurrent.**
- (b) Both  $x$  and  $y$  happened before  $z$ .
- (c) Both (a) and (b).
- (d) Neither (a) nor (b).

By looking at Lamport timestamps, we cannot tell the ordering:

If  $L(a) < L(b)$ , we don't know that  $a \rightarrow b$

However, if two events are causal ( $a \rightarrow b$ ) then  $L(a) < L(b)$

Two causal events will never have the same timestamps

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### Question 22

Which vector timestamp causally precedes  $\{4, 12, 26\}$  ?

- (a)  $\{3, 14, 28\}$
- (b)  **$\{4, 11, 26\}$**
- (c)  $\{5, 13, 27\}$
- (d)  $\{26, 12, 4\}$

- 
- (a)  $\{3, 14, 28\} \not\leq \{4, 12, 26\}$
  - (b)  **$\{4, 11, 26\} < \{4, 12, 26\}$**
  - (c)  $\{5, 13, 27\} > \{4, 12, 26\}$
  - (d)  $\{26, 12, 4\} \not\leq \{4, 12, 26\}$

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### Question 23

Which precedence vector from Process 2 can be given to the application immediately if the local vector is  $\{4, 12, 26\}$  (assume a vector of  $\{P_0, P_1, P_2\}$ )?

- (a)  **$\{4, 11, 27\}$**
- (b)  $\{4, 10, 28\}$
- (c)  $\{5, 13, 27\}$
- (d)  $\{3, 11, 28\}$

Rules

- Event counter not incremented for received messages
  - Increments element that corresponds to its entry (like vector timestamps)
  - Condition checks
    1. Message must be very next message from  $P_2$
    2. Message should not be causally dependent on any other message
- Every other element must be  $\leq$  corresponding local element:  
Check  $\forall i, i \neq \text{sender}: (V_{\text{sender}[i]} \leq V_{\text{receiver}[i]})$

(b) Missing message from  $P_2$ : 26, 28

(c) Causally greater: 13 is not  $\leq$  12

(d) Missing message from  $P_2$ : 26, 28

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### Question 24

Protocol Independent Multicast is used to:

- (a) Route IP multicast packets within the Internet.
- (b) Support multiple forms of multicast beyond IP multicast.
- (c) Provide sender-selectable levels of reliability in multicast streams.
- (d) Provide sender-selectable levels of reliability and message ordering in multicast streams.

(b): PIM just handles IP multicast

(c), (d): IP multicast does not offer varying levels of reliability

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### Question 25

Sparse Mode PIM has the advantage over Dense Mode multicast because it:

- (a) Does not funnel multicast traffic for a group through one designated router.
- (b) Supports different levels of message ordering and reliability service.
- (c) Does not require the use of IGMP.
- (d) Does not flood the network.

Rendezvous Point = designated address

- Routers from sender direct multicast messages toward the RP
- Routers from receivers direct multicast subscriptions toward the RP

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### Question 26

Virtual synchrony implements this form of multicast:

- (a) Atomic.
- (b) Reliable.
- (c) Unreliable.
- (d) Consistent.

Individual messages are generally sent via reliable multicast  
BUT

The *view change* operation ensures that all receivers have received all messages ... even if the sender dies

- *Stable vs. unstable* message
- *Flush* operation

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### Question 2

The two-army problem illustrates that, for an unreliable asynchronous network:

- (a) Two parties can come to agreement by sending messages through a third party.
- (b) Reliable communication requires acknowledging messages.
- (c) It is not necessary to acknowledge individual messages if you use cumulative acknowledgements.
- (d) An infinite series of messages is required to reach consensus.

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### Question 28

Although UDP guarantees reliable delivery, messages may arrive out of order.

False. UDP does not guarantee reliable delivery.

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### Question 29

Ethernet provides reliable delivery of packets

False.

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### Question 30

Because all code runs on a Java Virtual Machine, parameters do not need to be serialized with Java RMI.

**False.** Parameters need to be marshaled into a byte array that is sent to the remote system.

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### Question 31

Java uses remote reference counting for distributed garbage collection.

**False.** It uses leasing.

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### Question 32

With sync ordering, messages may sometimes arrive in a different order on different systems.

**True.** No specific message sequence is not guaranteed between sync operations.

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### Question 33

For a set of causal events, Lamport timestamps will identify their proper sequence.

**True.**

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### Question 34

Two events with identical Lamport timestamps must be concurrent.

**True.**

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### Question 35

A closed group means that no new members can join the group.

**False.** It means systems outside the group cannot send messages to the group.

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**Question 36**

The Precision Time Protocol is more accurate than NTP because it can deal with asymmetric network delays.

**False.** PTP assumes uplink and downlink delays are symmetric.

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**Question 37**

Two vector time stamps may be identical for concurrent events.

**False.**  $V_1 \neq V_2$

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The end

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