# **Operating Systems**

08. Real-Time Scheduling

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## What's wrong with priorities?

- Fixed priorities:
  - Should I be #4? ... #6? ... #15?
- Dynamic priorities
  - I have no idea what my priority is because the CPU changes it!

#### Real-time demands

- We don't always need a LOT of CPU time but we may need it at the right intervals
  - E.g., decode 30 frames per second of video

- We might have tight deadlines
  - E.g., complete task within the next 500 ms
- Conventional process scheduling algorithms focused on fairness, compromise, and providing the best overall experience

## Deadlines in real-time systems

- Start time (release time)
  - E.g., response to a sensor: start within 20 ms from sense time
- Stop time (deadline)
  - Scheduler must allot enough CPU time to complete
- Hard deadline
  - There is <u>no value</u> to the computation if it completes after the deadline
  - Safety critical system: critical start time and deadline
- Soft deadline
  - The value of a late result diminishes with time

## Process types

#### Terminating process

- Runs and exits (e.g., service a sensor event)
- How much time does it take to run to completion?
- Deadline = time to finish

#### Nonterminating process

- Interested in time between events
  - E.g., fill a 4 KB audio buffer every 500 ms
  - E.g., decode a video frame every 67 ms
- Compute time = time to compute periodic event
- Deadline = time to have periodic results ready

#### How much can we do?

- Don't expect magic
- E.g.,
  - decoding 1 video frame takes 20 ms
  - we want to decode 2 video frames at 30 frames/sec
  - We'll fail:  $2 \times 30 \times 20 = 1200 \text{ ms} > 1000 \text{ ms} (1 \text{ sec} = 1000 \text{ ms})$

• If T = period, D = deadline, C = compute time:  $C \le D \le T$ 

## Earliest Deadline Scheduling

- Each process tells OS its time deadline
- Scheduler picks the process in closest to its deadline
  - Usually one process runs to completion if it has an earlier deadline
  - Will be preempted if a process with an even earlier deadline starts

## Least Slack Scheduling

- Consider remaining time and deadline
- Look not only at the deadline but how much we can procrastinate

```
slack = (time to deadline) – (amount of computation)
```

• E.g., suppose

C (compute time) = 5 ms

D (deadline) = 20 ms from now

slack = D - C = 15 ms

#### Least Slack vs. Earliest Deadline First

#### **Earliest Deadline First**

We always work on the earliest deadline process and delay others

#### Least Slack

 Get a balanced result in that we keep the differences to deadlines balanced

#### If there's not enough time for everything:

- EDF: may hit only the early deadlines
- LS: all deadlines may be missed but roughly by the same amount

# Rate monotonic analysis

- Method of assigning static priorities to periodic processes
- Works with a static priority scheduler
- Must know all real-time processes running at the same time and their period
- Rate monotonic priority assignment is optimal
  - If the it is possible for all deadlines to be met then they will be met with rate monotonic assignment

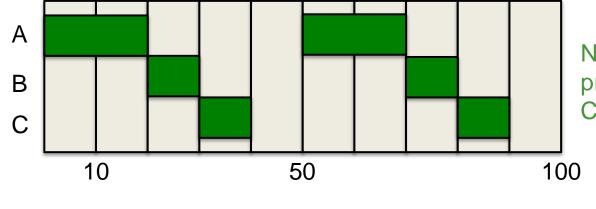
# Assigning priorities

- Highest frequency (smallest period) process gets the highest priority
- Successively lower frequency processes get lower priorities
- Scheduling is via a simple priority scheduler
- If two processes have the same priority, they can roundrobin

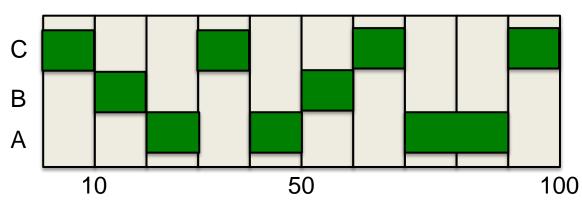
## Rate monotonic example

- Process A runs every 50 ms for 20 ms
- Process B runs every 50 ms for 10 ms
- Process C runs every 30 ms for 10 ms

Rate monotonic analysis: Schedule C first, then A or B



No rate monotonic priority assignment: C misses a period!



The End

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